

MAC 2103

Module 4

Vectors in 2-Space and 3-Space I

1

Learning Objectives

In this module, we apply our earlier ideas specifically to vectors in 2-space, \mathfrak{R}^2 , (in the xy-plane) in two dimensions and to vectors in 3-space, \mathfrak{R}^3 , (in the xyz-space) in three dimensions.

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Learning Objectives (Cont.)

Upon completing this module, you should be able to:

1. Determine the components of a vector in \mathbb{R}^2 and \mathbb{R}^3 .
2. Perform vector addition, subtraction, and scalar multiplication in \mathbb{R}^2 and \mathbb{R}^3 .
3. Find the norm of a vector and the distance between points in \mathbb{R}^2 and \mathbb{R}^3 .
4. Find the dot product of two vectors in \mathbb{R}^2 and \mathbb{R}^3 .
5. Use the dot product to find the angle between two vectors in \mathbb{R}^2 and \mathbb{R}^3 .
6. Find the projection of a vector onto another vector in \mathbb{R}^2 and \mathbb{R}^3 , and express the original vector as a sum of two orthogonal vectors.
7. Find the distance between a point and a line in \mathbb{R}^2 and \mathbb{R}^3 .

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Vectors in \mathbb{R}^2 and \mathbb{R}^3

There are three major topics in this module:

Introduction to Vectors (Geometric)
Norm of a Vector; Vector Operations
Dot Product; Projections

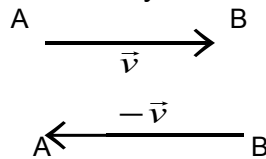
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What are Vectors in \mathbb{R}^2 and \mathbb{R}^3 ?

- Vectors can be represented as **directed line segments** or arrows in \mathbb{R}^2 and \mathbb{R}^3 .
- The direction of the arrow specifies the direction of the vector.
- A vector that starts from an initial point A and terminates at a point B can be represented as \overrightarrow{AB} .
- A vector is usually denoted in lowercase boldface type (like \mathbf{v}) in the textbook or with an arrow above it when we write it by hand. For example: $\mathbf{v} = \vec{v} = \overrightarrow{AB}$.



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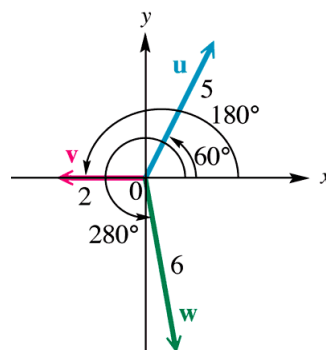
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What are Vectors in \mathbb{R}^2 and \mathbb{R}^3 ? (Cont.)

- The **magnitude** of the vector is the **length of the vector**.
- The vector of length zero is called the **zero vector**.
- Vectors with the same magnitude and same direction are equal to each other.
- A vector \mathbf{v} in standard position has its starting point at the origin. The **coordinates** (v_1, v_2) of the terminal point of \mathbf{v} are called the **components of \mathbf{v}** .

$$\mathbf{v} = \vec{v} = (v_1, v_2)$$



Note: The negative of vector \mathbf{v} is defined to be the vector that has the same magnitude as \mathbf{v} but is oppositely directed.

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What are Vectors in \mathcal{R}^2 and \mathcal{R}^3 ? (Cont.)

If s is any scalar, then a vector of the form $s\mathbf{v}$ is called a **scalar multiple** of \mathbf{v} .

$$s\mathbf{v} = s\vec{v} = s(v_1, v_2) = (sv_1, sv_2)$$

For example, if $\mathbf{v} = (2, -7)$ and $s = -5$, then

$$-5\vec{v} = -5(v_1, v_2) = (-5v_1, -5v_2) = (-10, 35)$$

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What are Vectors in \mathcal{R}^2 and \mathcal{R}^3 ? (Cont.)

• If \mathbf{v} and \mathbf{u} are any two vectors in standard position, then the **sum and difference of the two vectors** is also a vector. It's also a vector in standard position.

$$\mathbf{v} + \mathbf{u} = \vec{v} + \vec{u} = (v_1, v_2) + (u_1, u_2) = (v_1 + u_1, v_2 + u_2)$$

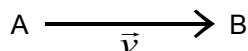
$$\mathbf{v} - \mathbf{u} = \vec{v} - \vec{u} = (v_1, v_2) - (u_1, u_2) = (v_1 - u_1, v_2 - u_2)$$

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What are the Components of a Vector in \mathbb{R}^3 ?



If the initial point of \overline{AB} is $A(x_1, y_1, z_1)$ and the terminal point of \overline{AB} is $B(x_2, y_2, z_2)$ in \mathbb{R}^3 , then the components of \overline{AB} can be obtained by subtracting the coordinates of the initial point from the coordinates of the terminal point.

$$\mathbf{v} = \vec{v} = \overline{AB} = (x_2 - x_1, y_2 - y_1, z_2 - z_1)$$

Example: Suppose the initial point of \overline{AB} is $A(1, -2, 5)$ and terminal point is $B(-1, 4, 9)$, then the components of the vector $\mathbf{v} = \vec{v} = \overline{AB} = (-2, 6, 4)$. We see that the vector \overline{AB} is equal to the vector \mathbf{v} in standard position.

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Example

Suppose $\vec{u} = (-5, 1, 6)$

$$\vec{v} = (1, 0, -8)$$

Find the components of $7\vec{u} - 2\vec{v}$.

$$\begin{aligned} 7\vec{u} - 2\vec{v} &= 7\vec{u} + (-2)\vec{v} = 7(-5, 1, 6) + (-2)(1, 0, -8) \\ &= ((7)(-5) + (-2)(1), (7)(1) + (-2)(0), (7)(6) + (-2)(-8)) \\ &= (-37, 7, 58) \end{aligned}$$

Note: In chapter 1, we would represent these vectors as column matrices:

$$\vec{u} = \begin{bmatrix} -5 \\ 1 \\ 6 \end{bmatrix} = \begin{bmatrix} -5 & 1 & 6 \end{bmatrix}^T \quad \vec{v} = \begin{bmatrix} 1 \\ 0 \\ -8 \end{bmatrix} = \begin{bmatrix} 1 & 0 & -8 \end{bmatrix}^T$$

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Some Important Properties of a Vector Space

If \mathbf{u} , \mathbf{v} , and \mathbf{w} are vectors in \mathfrak{R}^2 , \mathfrak{R}^3 , or any vector space and k and s are scalars, then the following hold:

- a) $\mathbf{u} + \mathbf{v} = \mathbf{v} + \mathbf{u}$ b) $(\mathbf{u} + \mathbf{v}) + \mathbf{w} = \mathbf{u} + (\mathbf{v} + \mathbf{w})$
c) $\mathbf{u} + \mathbf{0} = \mathbf{0} + \mathbf{u} = \mathbf{u}$ d) $\mathbf{u} + (-\mathbf{u}) = \mathbf{0}$
e) $k(s\mathbf{u}) = ks(\mathbf{u})$ f) $k(\mathbf{u} + \mathbf{v}) = k\mathbf{u} + k\mathbf{v}$
g) $(k + s)\mathbf{u} = k\mathbf{u} + s\mathbf{v}$ h) $1\mathbf{u} = \mathbf{u}$

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What is the Norm of a Vector in \mathfrak{R}^3 ?

- The **norm** of a vector \mathbf{u} , $\|\vec{u}\| = \|\mathbf{u}\|$, is the length or the **magnitude** of the vector \mathbf{u} .
- If $\mathbf{u} = (u_1, u_2, u_3) = (-1, 4, -8)$, then the norm of the vector \mathbf{u} is

$$\|\vec{u}\| = \sqrt{u_1^2 + u_2^2 + u_3^2} = \sqrt{(-1)^2 + 4^2 + (-8)^2} = 9$$

- This is just the distance of the terminal point to the origin for \mathbf{u} in standard position.

Note: If \mathbf{u} is any nonzero vector, then $\frac{\mathbf{u}}{\|\vec{u}\|}$ is a unit vector. A unit vector is a vector of norm 1.

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How to Find the Distance Between Two Points?

- If $A(x_1, y_1, z_1)$ and $B(x_2, y_2, z_2)$ are two points in \mathfrak{R}^3 , then the **distance** between the two points is the length, the magnitude, and the **norm of the vector** \overline{AB} .

$$d = \|\overline{AB}\| = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$$

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How to Find Dot Product of Two Vectors in Terms of the Components of the Vectors?

If $\mathbf{u} = (u_1, u_2, u_3)$ and $\mathbf{v} = (v_1, v_2, v_3)$, then the **dot product** of the two vectors in terms of the components of the vectors is:

$$\mathbf{u} \cdot \mathbf{v} = \vec{u} \cdot \vec{v} = u_1v_1 + u_2v_2 + u_3v_3 = \vec{u}\vec{v}^T$$

Example: If $\mathbf{u} = (3, 0, -1)$ and $\mathbf{v} = (2, 9, -2)$, then the **dot product** of the two vectors is:

$$\mathbf{u} \cdot \mathbf{v} = \vec{u} \cdot \vec{v} = (3)(2) + (0)(9) + (-1)(-2) = \begin{bmatrix} 3 \\ 0 \\ -1 \end{bmatrix} \begin{bmatrix} 2 & 9 & -2 \end{bmatrix}$$

$$= \vec{u}\vec{v}^T = 6 + 0 + 2 = 8$$

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How to Find the Angle Between Vectors?

By definition, if \mathbf{u} and \mathbf{v} are nonzero vectors in \mathfrak{R}^2 and \mathfrak{R}^3 and θ is the angle between \mathbf{u} and \mathbf{v} , then the dot product of the two vectors is:

$$\mathbf{u} \cdot \mathbf{v} = \vec{u} \cdot \vec{v} = \|\vec{u}\| \|\vec{v}\| \cos(\theta)$$

Thus, if \mathbf{u} and \mathbf{v} are nonzero vectors, the angle can be obtained by:

$$\cos(\theta) = \frac{\vec{u} \cdot \vec{v}}{\|\vec{u}\| \|\vec{v}\|}$$

Note: From the previous slide,

$$\cos(\theta) = \frac{\vec{u} \cdot \vec{v}}{\|\vec{u}\| \|\vec{v}\|} = \frac{8}{\sqrt{10} \sqrt{89}} .$$

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Some Important Properties of the Dot Product

If \mathbf{u} , \mathbf{v} , and \mathbf{w} are vectors in \mathfrak{R}^2 and \mathfrak{R}^3 and s is a scalar, then the following relationships hold:

a) $\mathbf{u} \cdot \mathbf{v} = \mathbf{v} \cdot \mathbf{u}$

b) $\mathbf{u} \cdot (\mathbf{v} + \mathbf{w}) = \mathbf{u} \cdot \mathbf{v} + \mathbf{u} \cdot \mathbf{w}$

c) $s(\mathbf{u} \cdot \mathbf{v}) = (s\mathbf{u}) \cdot \mathbf{v} = \mathbf{u} \cdot (s\mathbf{v})$

d) $\mathbf{v} \cdot \mathbf{v} = \vec{v} \cdot \vec{v} = \|\vec{v}\|^2$ and $\|\vec{v}\| = \sqrt{\mathbf{v} \cdot \mathbf{v}}$

e) $\mathbf{v} \cdot \mathbf{v} = \vec{v} \cdot \vec{v} = \|\vec{v}\|^2 > 0$ if and only if $\mathbf{v} \neq \mathbf{0}$, and $\mathbf{v} \cdot \mathbf{v} = 0$ iff $\mathbf{v} = \mathbf{0}$

If the vectors \mathbf{u} and \mathbf{v} are nonzero and θ is the angle between them, then $\theta = \pi/2$ if and only if $\mathbf{u} \cdot \mathbf{v} = 0$. Then,

\mathbf{u} and \mathbf{v} are **perpendicular** or **orthogonal**.

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How to Find the Projection of a Vector onto Another Vector?

If \mathbf{u} and \mathbf{v} are vectors in \mathbb{R}^2 and \mathbb{R}^3 and if $\mathbf{a} \neq \mathbf{0}$, then

$$\text{proj}_{\mathbf{a}} \mathbf{u} = \frac{\mathbf{u} \cdot \mathbf{a}}{\|\mathbf{a}\|^2} \mathbf{a} = \mathbf{u} \cdot \frac{\mathbf{a}}{\|\mathbf{a}\|} \frac{\mathbf{a}}{\|\mathbf{a}\|} \quad (\text{vector component of } \mathbf{u} \text{ along } \mathbf{a})$$

$$\mathbf{u} - \text{proj}_{\mathbf{a}} \mathbf{u} = \mathbf{u} - \frac{\mathbf{u} \cdot \mathbf{a}}{\|\mathbf{a}\|^2} \mathbf{a} \quad (\text{vector component of } \mathbf{u} \text{ orthogonal or perpendicular to } \mathbf{a})$$

Thus, the $\text{proj}_{\mathbf{a}} \mathbf{u}$ and $\mathbf{u} - \text{proj}_{\mathbf{a}} \mathbf{u}$ are orthogonal vectors whose sum is \mathbf{u} . The dot product of $\text{proj}_{\mathbf{a}} \mathbf{u}$ and $\mathbf{u} - \text{proj}_{\mathbf{a}} \mathbf{u}$ is zero.

$$\begin{aligned} (\text{proj}_{\mathbf{a}} \mathbf{u}) \cdot (\mathbf{u} - \text{proj}_{\mathbf{a}} \mathbf{u}) &= \left(\frac{\mathbf{u} \cdot \mathbf{a}}{\|\mathbf{a}\|^2} \mathbf{a} \right) \cdot \left(\mathbf{u} - \frac{\mathbf{u} \cdot \mathbf{a}}{\|\mathbf{a}\|^2} \mathbf{a} \right) = \\ \frac{(\mathbf{u} \cdot \mathbf{a})^2}{\|\mathbf{a}\|^2} - \frac{(\mathbf{u} \cdot \mathbf{a})^2 (\mathbf{a} \cdot \mathbf{a})}{\|\mathbf{a}\|^2 \|\mathbf{a}\|^2} &= \frac{(\mathbf{u} \cdot \mathbf{a})^2}{\|\mathbf{a}\|^2} - \frac{(\mathbf{u} \cdot \mathbf{a})^2}{\|\mathbf{a}\|^2} = 0 \end{aligned}$$

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How to Find the Projection of a Vector onto Another Vector and Express the Original Vector as the Sum of Two Orthogonal Vectors?

Example

Let $\mathbf{u} = (3, 1, -7)$ and $\mathbf{a} = (1, 0, 5)$. Find the vector component of \mathbf{u} along \mathbf{a} and the vector component of \mathbf{u} orthogonal to \mathbf{a} .

Solution:

Step 1: Find the dot product of the two vectors.

$$\mathbf{u} \cdot \mathbf{a} = \vec{u} \cdot \vec{a} = (3)(1) + (1)(0) + (-7)(5) = 3 + 0 + (-35) = -32$$

Step 2: Find the norm of \mathbf{a} .

$$\|\mathbf{a}\| = \|\vec{a}\| = \sqrt{(1)^2 + (0)^2 + (5)^2} = \sqrt{1 + 0 + 25} = \sqrt{26}$$

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How to Find the Projection of a Vector onto Another Vector? (Cont.)

Step 3: Solve for the vector component of \mathbf{u} along \mathbf{a} .

$$\text{proj}_{\mathbf{a}} \mathbf{u} = \frac{\mathbf{u} \cdot \mathbf{a}}{\|\mathbf{a}\|^2} \mathbf{a} = \frac{-32}{26} \mathbf{a} = \frac{-16}{13} (1, 0, 5) = \left(\frac{-16}{13}, 0, \frac{-80}{13} \right)$$

Step 4: Solve for the vector component of \mathbf{u} orthogonal to \mathbf{a} .

$$\mathbf{u} - \text{proj}_{\mathbf{a}} \mathbf{u} = (3, 1, -7) - \left(\frac{-16}{13}, 0, \frac{-80}{13} \right) = \left(\frac{55}{13}, 1, \frac{-11}{13} \right)$$

Note: $(\mathbf{u} - \text{proj}_{\mathbf{a}} \mathbf{u}) + \text{proj}_{\mathbf{a}} \mathbf{u} = \left(\frac{55}{13}, 1, \frac{-11}{13} \right) + \left(\frac{-16}{13}, 0, \frac{-80}{13} \right)$
 $= \left(\frac{39}{13}, 1, \frac{-91}{13} \right) = (3, 1, -7) = \mathbf{u}$

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How to Find the Projection of a Vector onto Another Vector? (Cont.)

Step 5: Check to see if the two component vectors are orthogonal.

$$\text{proj}_{\mathbf{a}} \mathbf{u} = \frac{\mathbf{u} \cdot \mathbf{a}}{\|\mathbf{a}\|^2} \mathbf{a} = \frac{-32}{26} \mathbf{a} = \frac{-16}{13} (1, 0, 5) = \left(\frac{-16}{13}, 0, \frac{-80}{13} \right)$$

$$\mathbf{u} - \text{proj}_{\mathbf{a}} \mathbf{u} = (3, 1, -7) - \left(\frac{-16}{13}, 0, \frac{-80}{13} \right) = \left(\frac{55}{13}, 1, \frac{-11}{13} \right)$$

$$(\text{proj}_{\mathbf{a}} \mathbf{u}) \cdot (\mathbf{u} - \text{proj}_{\mathbf{a}} \mathbf{u}) = \left(\frac{-16}{13}, 0, \frac{-80}{13} \right) \cdot \left(\frac{55}{13}, 1, \frac{-11}{13} \right)$$

$$= \frac{-880}{169} + 0 + \frac{880}{169} = 0$$

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How to Find the Distance Between a Point and a Line?

Example

Find the distance D from the point $(-3,1)$ to the line $4x+3y+4=0$.

Solution:

We can use the distance formula in Equation (13)

$$D = \frac{|ax_0 + by_0 + c|}{\sqrt{a^2 + b^2}}$$

to find the distance D . In our problem, $x_0=-3$, $y_0=1$, $a=4$, $b=3$, and $c=4$.

$$D = \frac{|ax_0 + by_0 + c|}{\sqrt{a^2 + b^2}} = \frac{|(4)(-3) + (3)(1) + 4|}{\sqrt{4^2 + 3^2}} = \frac{|-5|}{5} = \frac{5}{5} = 1$$

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What have we learned?

We have learned to:

1. Determine the components of a vector in \mathbb{R}^2 and \mathbb{R}^3 .
2. Perform vector addition, subtraction, and scalar multiplication in \mathbb{R}^2 and \mathbb{R}^3 .
3. Find the norm of a vector and the distance between points in \mathbb{R}^2 and \mathbb{R}^3 .
4. Find the dot product of two vectors in \mathbb{R}^2 and \mathbb{R}^3 .
5. Use the dot product to find the angle between two vectors in \mathbb{R}^2 and \mathbb{R}^3 .
6. Find the projection of a vector onto another vector in \mathbb{R}^2 and \mathbb{R}^3 , and express the original vector as a sum of two orthogonal vectors.
7. Find the distance between a point and a line in \mathbb{R}^2 and \mathbb{R}^3 .

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Credit

Some of these slides have been adapted/modified in part/whole from the text or slides of the following textbooks:

- Anton, Howard: Elementary Linear Algebra with Applications, 9th Edition
- Margaret L. Lial, John Hornsby, David I. Schneider, Trigonometry, 8th Edition